

Bio-inspired soft robotics for underground exploration

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1st year at 3SR

Characterizing root-soil interaction (in the presence of obstacles) using tomography

2nd year at IIT(Genova)

Building up robots with single functions

3rd year at 3SR

Characterizing soil-robot interactions using tomography

The research team includes:
Nicolas LENOIR and Robert PEYROUX (3SR)



Agar



Maize seed





Plantoid in IIT



two-layer soil (previous work)



root trajectory from x-ray tomo









